

**Amendments to the Specification:**

On Page 1, before the first paragraph, please add the following paragraphs:

**BACKGROUND OF THE INVENTION**

1. Field of the Invention

On Page 1, after the first full paragraph, please add the following paragraph:

2. Description of the Related Art

On Page 3, before the first full paragraph, please add the following paragraph:

**SUMMARY OF THE INVENTION**

On Page 8, please replace the first full paragraph with the following rewritten paragraph:

Preferably, the set of bellows consists of rubber or another suitable, for example rubber-like plastic, which has a relatively great rigidity of more than 65 Shore, for example approximately 70 Shore, according to the DIN 53505 standard published in 2000. Because of this rigidity of the material of the set of bellows, the ability of the set of bellows to withstand stress is

increased, and the deformations that occur during operation are limited.

On Page 9, after the paragraph bridging pages 8 and 9, please add the following paragraph:

BRIEF DESCRIPTION OF THE DRAWINGS

On Page 9, please replace the next-to-last full paragraph with the following rewritten paragraph:

~~Fig.~~ FIG. 1 shows a fixed homokinetic joint having a sealing arrangement, in a cross-sectional view~~i~~, ~~and~~

On Page 9, please replace the last full paragraph with the following rewritten paragraph:

~~Fig.~~ FIG. 2 shows details of a displaceable homokinetic joint having a sealing arrangement, in a cross-sectional view~~i~~ -

On Page 9, before the paragraph bridging pages 9-10, please add the following new paragraphs:

FIG. 3 shows the embodiment of FIG. 1 with the operational incline angle indicated;

FIG. 4 shows the embodiment of FIG. 1 with the installation incline angle indicated;

FIG. 5 shows a fixed homokinetic joint with a spring ring fixing the bellows in place on the inner hub;

FIG. 6 shows a fixed homokinetic joint with a strap fixing the bellows in place on the inner hub;

FIG. 7 shows a fixed homokinetic joint with a sheet-metal ring vulcanized into the radially inner edge of the bellows and the bellows drawn onto the outer hub with a press fit, and the carrier housing connected with a shaft; and

FIG. 8 shows a fixed homokinetic joint with the inner hub connected with a shaft.

#### DETAILED DESCRIPTION OF PREFERRED EMBODIMENTS

On Page 11, please replace the first full paragraph with the following paragraph:

A set of bellows 11 is disposed on the left side of the homokinetic joint 1, in ~~the figure~~ FIG. 1. The set of bellows 11 has a radially inner edge 11a that is fixed in place on the inner hub 2 during operation by means of a tie 12. In this connection, the tie 12 holds the inner edge 11a of the set of bellows 11 fixed in place on the inner hub 2, in such a manner that slipping

of the set of bellows on the inner hub does not occur during operation of the homokinetic joint 1. The radially outer edge 11b of the set of bellows 11 is attached to a cap 13 that surrounds the carrier housing 9 and the outer hub 3, by means of a crimp 14. The cap 13 furthermore has a section 13a that projects away from the outer hub 3, which section follows the crimp 14. The section 13a is configured essentially as a cylinder, and extends up to the vicinity of the region in which the set of bellows 11 is fixed in place on the inner hub 2 by means of the tie 12, in the axial direction of the inner hub 2, in the installed position. Therefore the section 13a forms an essentially smooth contact surface for the set of bellows 11, when the latter is pressed outward due to centrifugal forces.

On Page 11, after the first full paragraph, please insert the following new paragraph:

The bellows, 11 in the embodiment shown in FIG. 1 and 16 in the embodiment shown in FIG. 2, can be made of rubber or a rubber-type plastic with a hardness of approximately 70 Shore, according to the DIN 53505 standard published in 2000.

On Page 13, after the last paragraph please add the following new paragraphs:

FIG. 3 shows the operational incline angle of a fixed homokinetic joint according to the invention. The operational incline angle equals  $\alpha_o + \beta_o$ . FIG. 4 shows the installation incline angle of a fixed homokinetic joint according to the invention. The installation incline angle equals  $\alpha_I + \beta_I$ .

FIG. 5 shows a fixed homokinetic joint with a radially inner edge 11a of the bellows 11 fixed in place on the inner hub 2 during operation by means of a strap 12a. FIG. 6 shows a fixed homokinetic joint with a radially inner edge 11a of the bellows 11 fixed in place on the inner hub 2 during operation by means of a spring ring 12b.

FIG. 7 shows a fixed homokinetic joint with a sheet-metal ring 12c vulcanized into the radially inner edge 11a of the bellows 11 and the radially inner edge 11a of the bellows 11 drawn onto the inner hub 2 with a press fit. FIG. 7 also shows the carrier housing 9 connected with shaft 19. FIG. 8 shows outer hub 3 connected with shaft 19. In FIGS. 7 and 8, the bellows 11 is disposed on a transmission or differential side of the joint.

On page 14, please replace the Reference Symbol List with the following rewritten Reference Symbol List:

- 1           fixed homokinetic joint
- 1'          displaceable homokinetic joint
- 2, 2'       inner hub
- 3           outer hub
- 4           track of the inner hub
- 5           track of the outer hub
- 6           ball
- 7           cage
- 8           inner profiling
- 9, 9'       carrier housing
- 10          closure lid
- 11          set of bellows
- 11a         radially inner edge of the set of bellows
- 11b         radially outer edge of the set of bellows
- 12          tie
- 12a        strap
- 12b        spring ring
- 12c        sheet-metal ring
- 13          cap
- 13a, 13a'   section of the cap
- 14          crimp
- 15          pleat

16            set of bellows  
17            pleat  
18            pleat  
19           shaft

In the Abstract, please replace the Abstract currently on file with the amended Abstract attached hereto on its own separate sheet.